# Workshop Cargèse Trends in physical and numerical modeling of multiphase flows, CFD and its experimental validation for multiphase flows IESC Cargèse 2012, sep 24-28 2012

# Lagrange-remap solver and low-diffusive interface capturing for air-water flows

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#### **Outline**

- 1. System of interest
- 2. Numerical method
- 3. Antidiffusive procedure for the interface
- 4. Numerical experiments & validation
- 5. Concluding remarks

# System of interest

- Air-water multifluid flow
- Viscous effects neglected
- Surface tension neglected

 Transport equation to track the mass gas fraction transport c<sub>g</sub>

 « Three-equation » volume averaged model (one velocity) with pressure equilibrium closure

# Scope, applications, project

- Wave breaking/wave impact analysis
- Pressure impact under sloshing conditions
- Pipe flows

- ... a milestone before including more Physics (viscosity, surface tension, ...)
- ... prototype multiphase code solver suitable for GPU parallel computing.

# System of equations

- Isentropic Euler system for gas
- Isentropic Euler system for (compressible) liquid
- + interface (kinematic/dynamic) conditions

Trick: make use of a colored fluid function

$$\partial_t z + \boldsymbol{u} \cdot \nabla z = 0, \quad z \in \{0, 1\}.$$

Numerical approach: consider

$$\partial_t z + \boldsymbol{u} \cdot \nabla z = 0, \quad \boldsymbol{z} \in [0, 1]$$

Use the mass gas fraction for example as color function:

$$\partial_t c_g + \mathbf{u} \cdot \nabla c_g = 0, \quad c_g = \frac{\alpha \rho_g}{\rho}$$
  
 $\alpha = \text{gas void fraction}, \quad \rho = \alpha \rho_q + (1 - \alpha)\rho_\ell.$ 

We get mass conservation per phase :

$$\partial_t (\alpha \rho_g) + \nabla \cdot (\alpha \rho_g \mathbf{u}) = 0,$$
$$\partial_t ((1 - \alpha)\rho_\ell) + \nabla \cdot ((1 - \alpha)\rho_\ell \mathbf{u}) = 0,$$

+ momentum equation

$$\partial_t(\rho \boldsymbol{u}) + \nabla \cdot (\rho \boldsymbol{u} \otimes \boldsymbol{u}) + \nabla p = \rho \boldsymbol{g}$$

• + closure : pressure equilibrium closure:

$$p = p_g(\rho_g) = p_\ell(\rho_\ell) \longrightarrow \varphi(\alpha) = 0.$$

# Choice of the EOS for each fluid

For the gas phase, we use a perfect gas law:

$$p_g(\rho_g) = p^0 \left(\frac{\rho_g}{\rho_g^0}\right)^{\gamma_g}, \quad \gamma_g = 1.4, \ \rho_g^0 = 1.28 \ kg/m^3, \ p^0 = 10^5 \ Pa.$$

 For the water: we use a modified Tait equation for the liquid

$$p_{\ell}(\rho_{\ell}) = p^{0} \left\{ 1 + K \left[ \left( \frac{\rho_{\ell}}{\rho_{\ell}^{0}} \right)^{\gamma_{\ell}} - 1 \right] \right\}, \quad K = \frac{\rho_{\ell}^{0} c_{s}^{2}}{p^{0} \gamma_{\ell}}$$

with for instance:  $\gamma_l = 3.5$ ,  $\rho_l^0 = 1000$ ,  $c_s = 350 \text{ m.s}^{-1}$ , (K = 350)

NB: weakly compressible: if  $p = \frac{p^0}{2}$ , then  $ho_\ell = 999.59$ 

# Pressure equilibrium equation

• From the knowledge of the conservative variables  $W_g=\alpha\rho_g$  and  $W_g=(1-\alpha)\rho_g$  , we have to solve :

$$p_g(\rho_g) = p_\ell(\rho_\ell)$$

i.e.

$$\varphi(\alpha) = \left(\frac{W_g}{\alpha \rho_g^0}\right)^{\gamma_g} - 1 - K\left[\left(\frac{W_\ell}{(1-\alpha)\rho_\ell^0}\right)^{\gamma_\ell} - 1\right] = 0, \quad \alpha \in ]0,1[.$$

• NB: very stiff function, the choice of the iterative solver requires attention (initial guess, surrogates, Newton, etc.)

In fact, there is a trick ...:

### Trick for initial guess:

 The liquid mass conservation equation can be written in the form :

$$\partial_t (1 - \alpha) + \nabla \cdot [(1 - \alpha) \boldsymbol{u}] = -\frac{D_t \rho_\ell}{\rho_\ell}.$$

 Under the weak compressibility assumption or the liquid phase, we get

$$\partial_t \alpha + \nabla \cdot (\alpha \boldsymbol{u}) = 0.$$

- A numerical scheme is applied to this additional ``guess equation" to compute initial guesses of the iterative solver
  - → Newton algorithm converges in 2 iterates with acceptable accuracy (strong improvement in CPU time).

# Numerical scheme

# Lagrange-remap strategy

First write the equations in Lagrangian form

$$\frac{d}{dt} \int_{\Omega_t} \alpha \rho_g \, dx = 0,$$

$$\frac{d}{dt} \int_{\Omega_t} (1 - \alpha) \rho_\ell \, dx = 0,$$

$$\frac{d}{dt} \int_{\Omega_t} \rho \boldsymbol{u} \, dx + \int_{\Omega_t} \nabla p \, dx = \int_{\Omega_t} \rho \boldsymbol{g}.$$

(Lagrange integral form here)

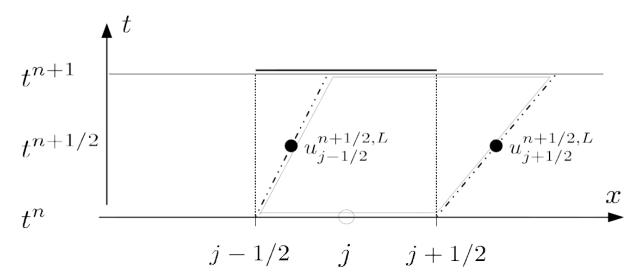
- Integrate them in time over a time step
- Project the quantities on the fixed Eulerian grid (remap)

#### Conservative form

- Lagrange-remap schemes can be rewritten actually in conservative form [De Vuyst et al, CRAS Mécanique 2012].
- 1D case :

$$(\alpha \rho_g)_j^{n+1} = (\alpha \rho_g)_j^{n+1} - \frac{\Delta t}{h} \left[ (\Phi_{m,g})_{j+1/2}^{n,n+1} - (\Phi_{m,g})_{j-1/2}^{n,n+1} \right],$$

$$(\Phi_{m,g})_{j+1/2}^{n,n+1} = \alpha_{j+1/2}^{n+1,L} (\rho_g)_{j+1/2}^{n+1,L} u_{j+1/2}^{n+1/2,L}$$



# Antidiffusive strategy

$$(\alpha \rho_g)_j^{n+1} = (\alpha \rho_g)_j^{n+1} - \frac{\Delta t}{h} \left[ (\Phi_{m,g})_{j+1/2}^{n,n+1} - (\Phi_{m,g})_{j-1/2}^{n,n+1} \right],$$
 
$$(\Phi_{m,g})_{j+1/2}^{n,n+1} = \alpha_{j+1/2}^{n+1,L} (\rho_g)_{j+1/2}^{n+1,L} u_{j+1/2}^{n+1/2,L}$$
 Void fraction at interface : how to compute it ?

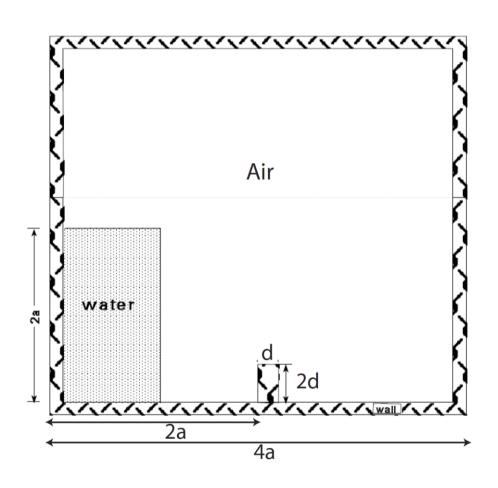
- Strategy: « be as sharpest as possible for step-shaped color functions while staying stable (just at the limit) »
- Idea: design a combination of upwinding scheme and downwind scheme [Lagoutière Després 2002, Kokh-Lagoutière 2010]
- The advection process can be seen as a over-compressive « limiting » procedure (superbee-like, hyperbee, ...)

#### Test cases

and numerical experiments

(+ comparison to physical experiments for some of them)

# 1. Collapse of a liquid column with an obstacle



O. Ubbink Numerical prediction of two-fluid systems with sharp interfaces, PhD thesis (1997)

$$a = 0.146 \text{ m}, d = 0.024 \text{ m}$$

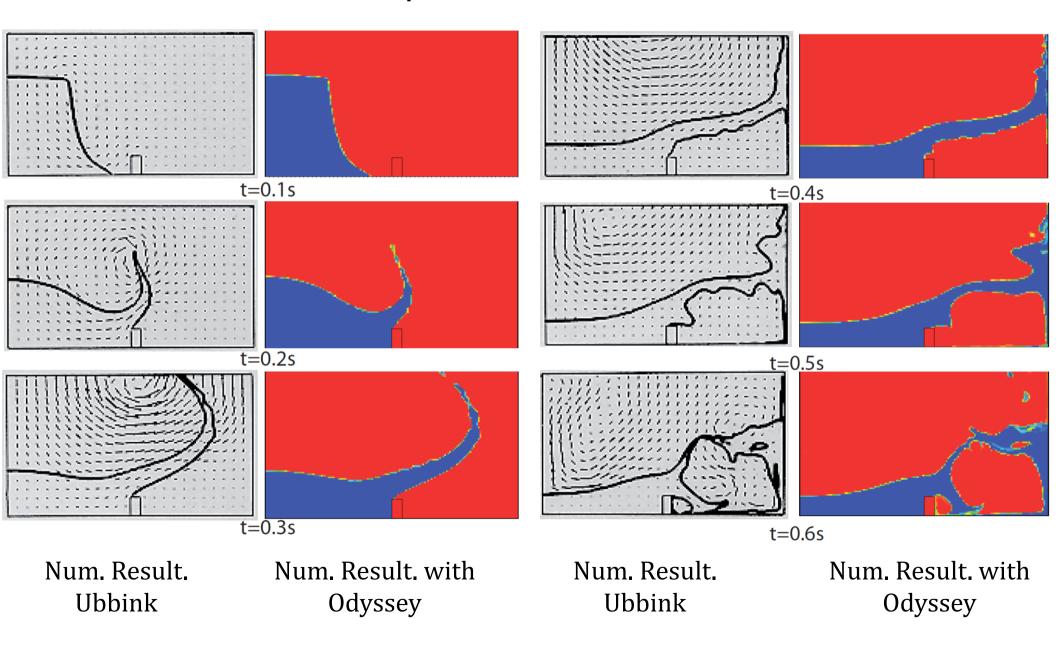
$$Nx = Ny = 150$$

$$\gamma_g = 1.4, \gamma_l = 7$$

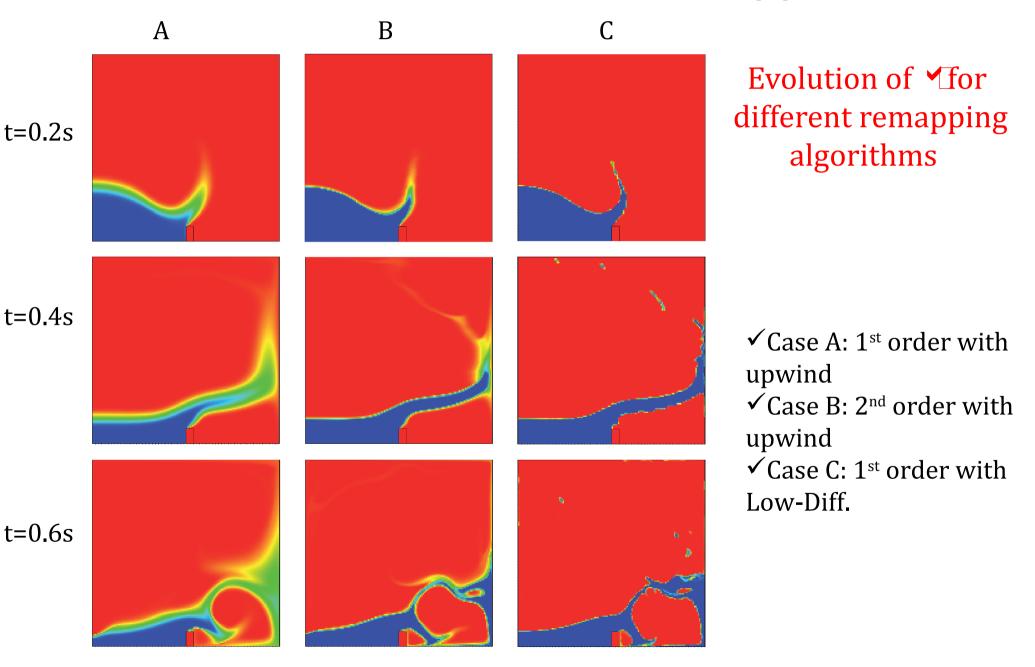
$$\rho_0^g = 1.28 \text{ kg.m}^{-3}, \rho_0^l = 1000 \text{ kg.m}^{-3}$$

$$P_0 = 10^5, c_{\text{sound}} = 350 \text{ m.s}^{-1}$$

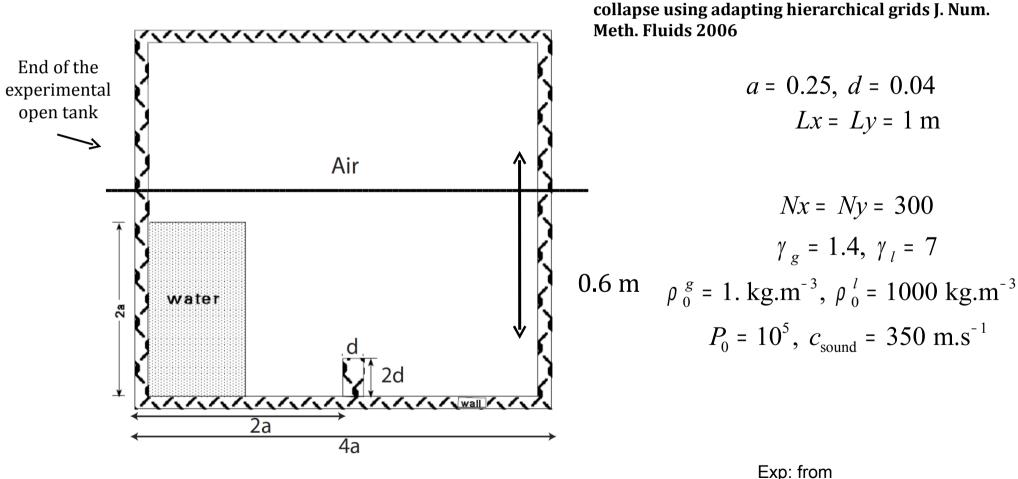
# Collapse with an obstacle – comparison with incompressible fluid model



# Benefits of the antidiffusive approach



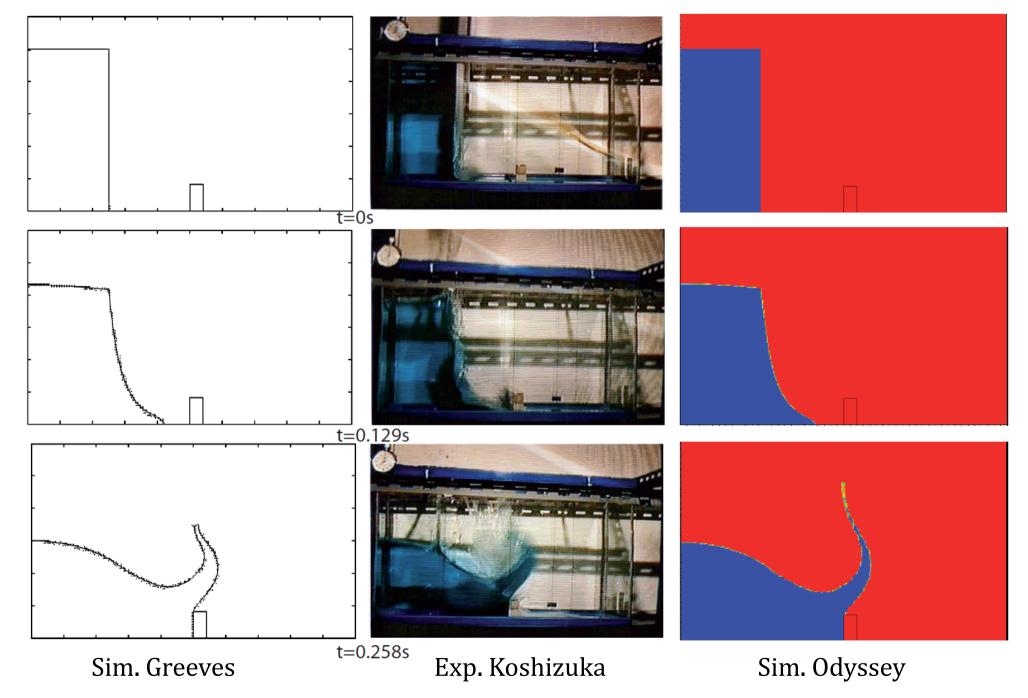
# Another case of collapse of a liquid column with an obstacle



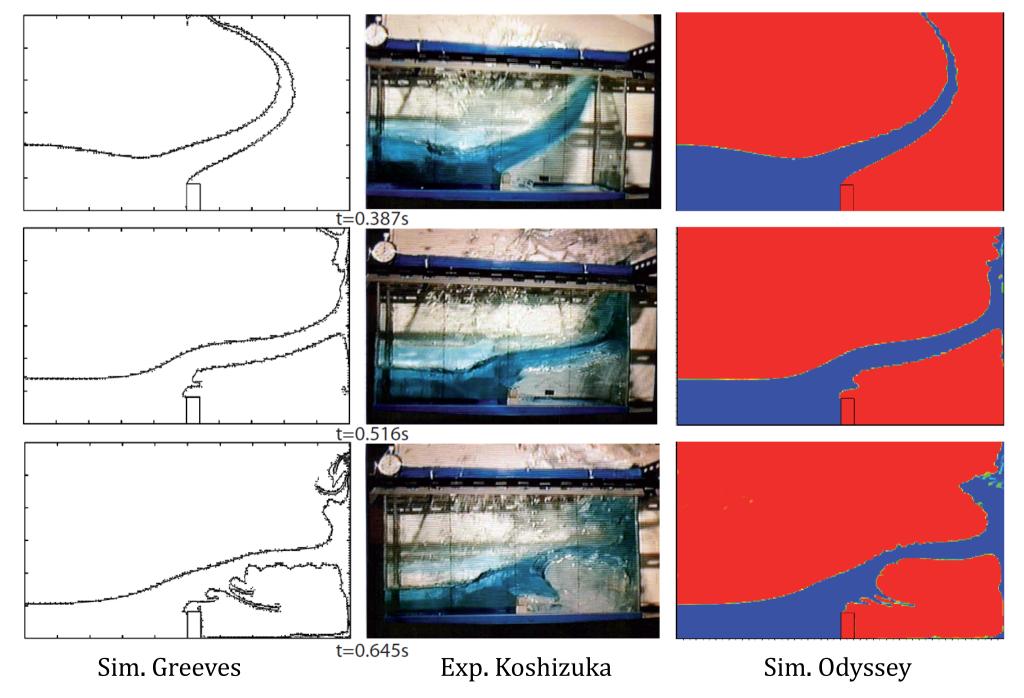
Koshizuka et al A particle method.. Comp. Fluid Mech. 1995

D. M. Greeves Simulation of viscous water column

# Simulations of a dam break

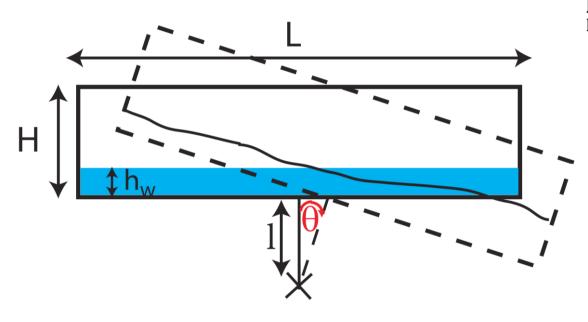


# Simulations of a dam break



# Sloshing test cases – pitch motion

 Sloshing due to the pitch motion of a rectangular tank:



J.R. Shao *et al* . An improved SPH method for modeling liquid sloshing dynamics. Comp. Fluids 2012

$$L = 0.64m$$
,  $H = 0.14m$ ,  $h_w = 0.03m$   
 $Nx = 300$ ,  $Ny = 67$ 

The tank is oscillating as a **pendulum** according to:

$$\theta(t) = \theta_0 \sin(\omega_r t)$$

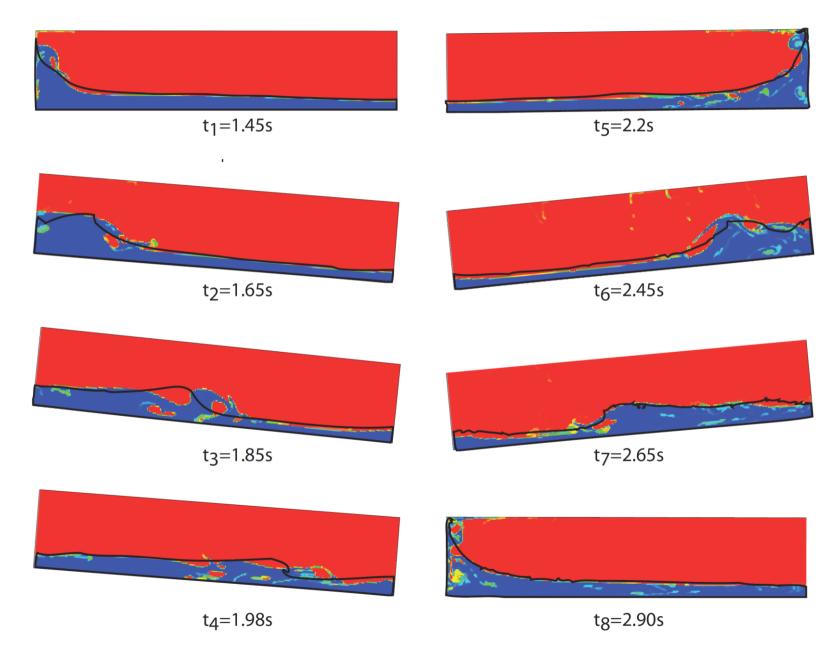
with 
$$\theta_0 = 6^{\circ}$$
,  $\omega_r = 4.34 \text{ rad/s} (T = 1.45 \text{ s})$ 

Simulation are performed in the frame of reference of the tank.

# Comparison SPH – present method

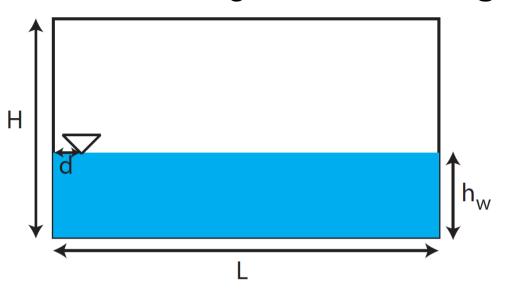
We superimpose the profile of the article:

J.R. Shao  $\it et al$  . An improved SPH method for modeling liquid sloshing dynamics. Comp. Fluids 2012



# Sloshing test cases – surge motion

Sloshing due to the surge motion of a rectangular tank:



J.R. Shao  $\it et al$  . An improved SPH method for modeling liquid sloshing dynamics. Comp. Fluids 2012

$$L = 1.73m$$
,  $H = 1.15m$ ,  $h_w = 0.6m$   
 $d = 0.05$  m  
 $Nx = 173$ ,  $Ny = 115$ 

The tank is moving horizontally according to:

$$x(t) = A \, \cos \left(\frac{2\pi t}{T}\right)$$
 with  $A=0.032$  m,  $T=1.3$  s  $(\omega_{forced}=4.83$  rad/s).

Two frequencies are acting  $\omega_{
m fluid}$  and  $\omega_{
m forced}$ 

First natural frequency of the fluid in the box

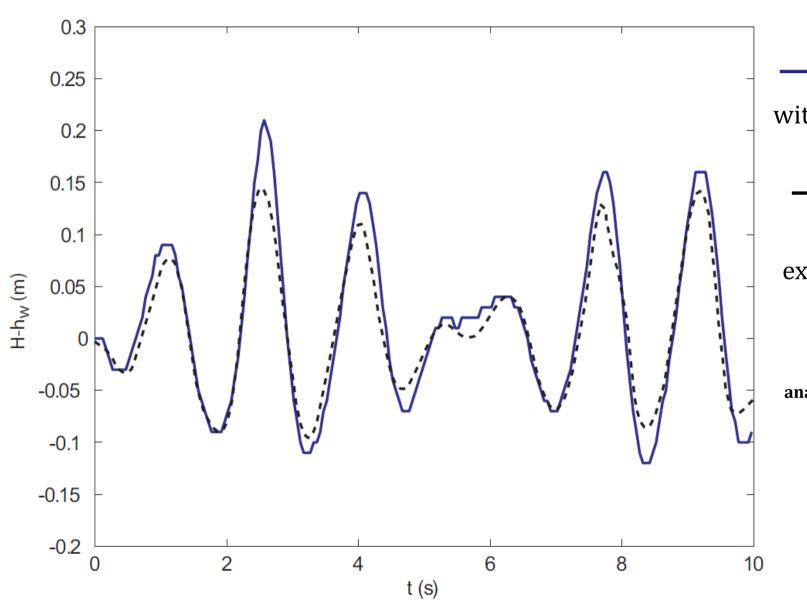
$$\omega_{fluid} = \sqrt{g \frac{\pi}{L} \tanh(\frac{\pi}{L} h_w)} \approx 3.77 \text{ rad/s}$$

Experimentals results are available:

O.M. Faltinsen *et al* . Multidimensional modal analysis... J. Fluid. Mechanics 2000

# Sloshing test cases – surge motion

#### Free surface elevation of water at the probe



with our code

Scanned experimental results of

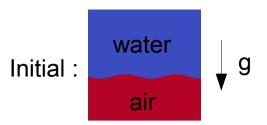
O.M. Faltinsen *et al* . Multidimensional modal analysis... J. Fluid. Mechanics 2000

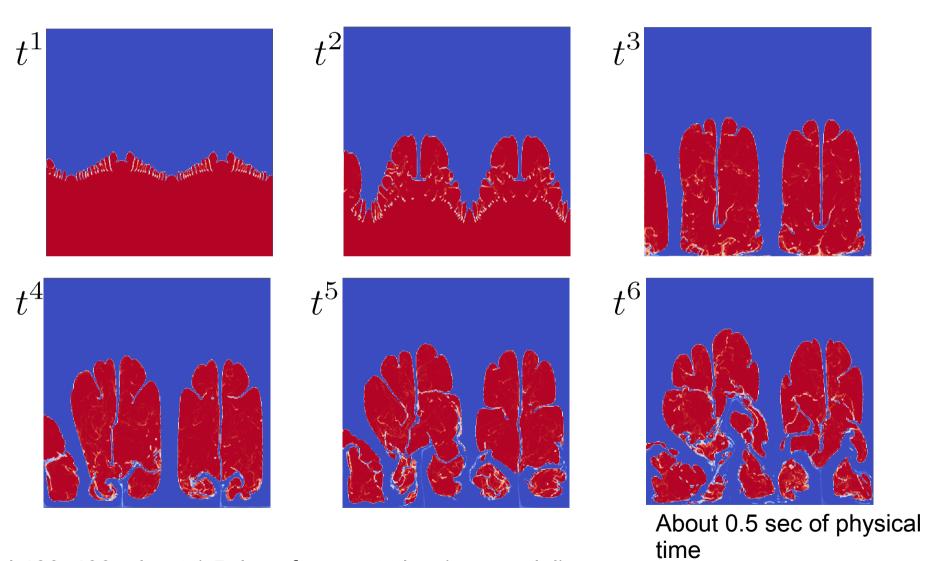
# Sloshing test cases – surge motion

We search to find a fit of our curve with a function as a superposition of two signals

 $f(t) = A_1 \sin(f_1 t + \varphi_1) + A_2 \sin(f_2 t + \varphi_2)$ we get:  $f_1 = 3.74 \pm 0.01 \text{ rad/s}$ ,  $f_2 = 4.83 \pm 0.01 \text{ rad/s}$ **very close to**  $\omega_{\text{fluid}} \approx 3.77 \text{ rad/s}$  and  $\omega_{\text{forced}} = 4.83 \text{ rad/s}$ 0.20 Coefficient values  $\pm$  one standard deviation  $=-0.080534 \pm 0.0014$ 0.15  $=1.5875 \pm 0.0426$  $=0.011949 \pm 0.000963$ =0.066601 ± 0.00139 0.10 0.05 0.00 -0.05 -0.10 2 10

#### LT air-water Rayleigh-Taylor instability





Grid 400x400, about 1.5 day of computation (sequential)

# Concluding remarks

- Innovative numerical Eulerian method involving :
  - a Lagrange-Remap finite volume method
  - an anti-diffusive approach and the void fraction to keep a thin interface between the two fluids
- The test cases show a good agreement between XP and other codes (dam break, sloshing events)

- Ongoing works: XP + num of water wave wall impact (Luc Lenain, Ken Melville, U. Delaware San Diego, Frédéric Dias, U. College Dublin).
- Need to add: physical viscosity, surface tension for further investigation and validation
- GPU parallel computation

Some videos ...

# Papers & videos

 A. Bernard-Champmartin, F. De Vuyst, « A low diffusive Lagrange-Remap scheme for the simulation of violent air-water free-surface flows », under progress, to submit to J. Comput. Phys. (2012)

 A. Bernard-Champmartin, F. De Vuyst, A low diffusive Lagrange-remap scheme for the simulation of violent air-water free-surface flows. Applications to dam-break and sloshing events, in preparation.

Videos :

http://www.youtube.com/user/floriandevuyst/videos



## Thank you for your attention